

Cluster 3: Networked Software Systems

Coordinating Shared Media Access through Counter-Phase Coupling

Christoph Angerer

Laboratory for Software Technology, ETH Zürich

Background: Peskin's Model for Self-Synchronization [1]

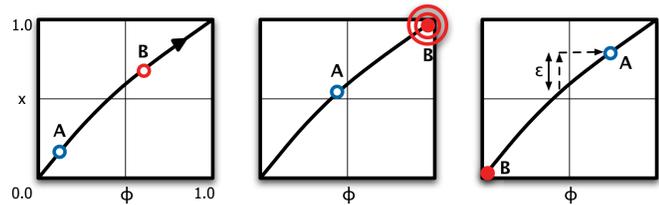


Figure 1: A system of two oscillators interacting by the pulse-coupling rule (see [1])



Network of N integrate-and-fire oscillators.

Voltage-like state variable x_i with dynamics:

$$\frac{dx_i}{dt} = S_0 - \gamma x_i, \quad 0 \leq x_i \leq 1, \quad i = 1, \dots, N$$

When $x_i = 1$, the i -th oscillator fires and $x_i \rightarrow 0$

Pulse (or phase) coupling: a firing oscillator pulls other oscillators up by an amount ϵ or to firing:

$$x_i(t) = 1 \Rightarrow x_j(t^+) = \min(1, x_j(t) + \epsilon) \quad \forall j \neq i$$

For arbitrary initial conditions: system approaches a state in which all oscillators are firing synchronously.

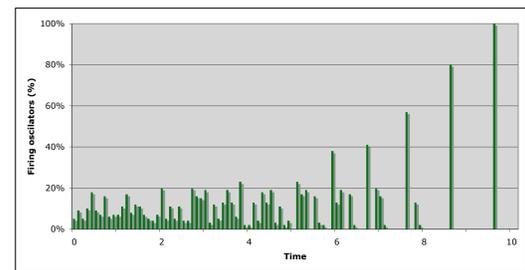


Figure 2: Number of oscillators firing over time; $N=100$, $S_0=2$, $\gamma=1$, $\epsilon=0.3$ (see [1])

Application to Wireless Networks [2]

Problem: transmission delays cause "blind spots" where no mutual coupling between nodes can occur.

Here, lower bound for synchronization accuracy is: $T_{del} = T_0 + T_{Tx} + T_{dec}$

T_0 : propagation delay

T_{Tx} : transmitting delay (Message length)

T_{dec} : decoding delay

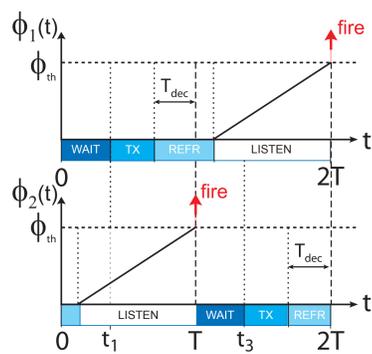


Figure 3: Timing advance strategy for two periods (see [2])



Solution: nodes delay sending the synchronization burst by:

$$T_{wait} = T - (T_{Tx} + T_{dec})$$

Oscillators split into two groups, firing T seconds apart, synchronizing each other.

Accuracy only bounded by T_0 .

Plan: Counter-Phase Coupling for Coordinated Media Access

Idea: "counter"-phase coupling creates groups that access the shared medium simultaneously without interference.

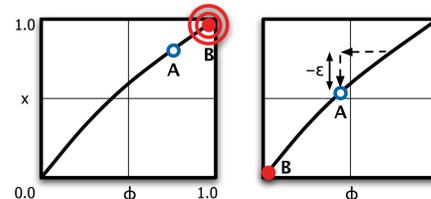


Figure 4: Two oscillators interacting by the counter-phase-coupling rule

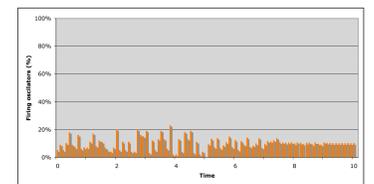


Figure 5: Oscillators firing with counter-phase-coupling

Goal: more "coordinated" alternative to randomized backoff strategies with no communication overhead.

Hypothesis: Pro-active collision avoidance increases throughput and fairness under high load.

Plan: Realization as MAC-layer add-on; evaluation on NS-2 and on our testbed.

Other potential applications: accessing shared media with expensive collision handling; e.g., memory, databases.

[1] R.E. Mirollo, S.H. Strogatz, Synchronization of Pulse-Coupled Biological Oscillators, SIAM J. APPL. Math, Vol 50, 1990

[2] A. Tyrrell, G. Auer, C. Bettstetter, Firefly Synchronization in Ad Hoc Networks, Proc. MINEMA workshop, Belgium, 2006